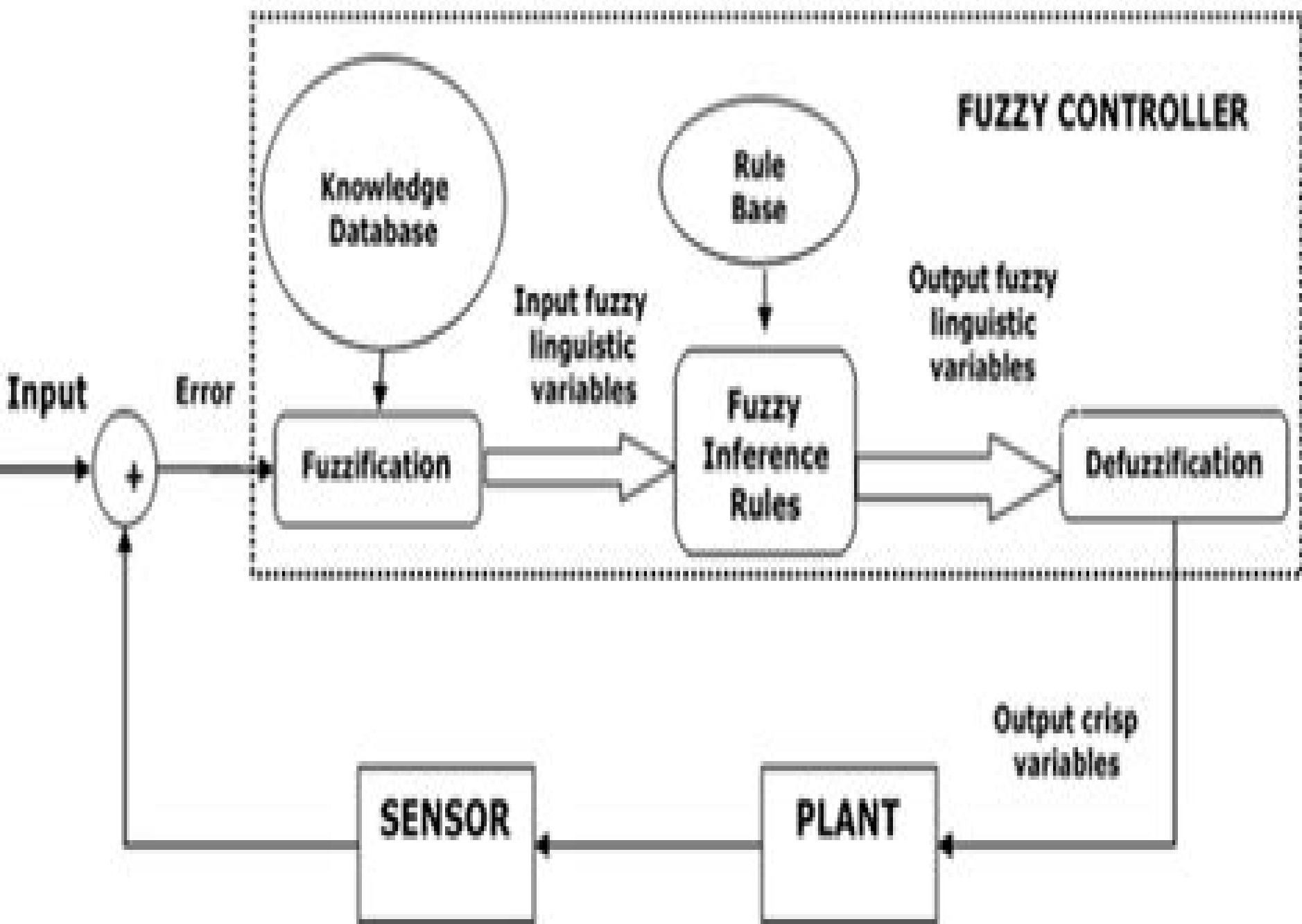




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Dianwei Qian,Jianqiang Yi



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Design of a Fuzzy Logic Controller for Swing-damped Transport of an Overhead Crane Payload Michael J. Nalley,1996 **Hierarchical Sliding Mode Control for Under-actuated Cranes** Dianwei Qian,Jianqiang Yi,2015-10-15 This book reports on the latest developments in sliding mode overhead crane control presenting novel research ideas and findings on sliding mode control SMC hierarchical SMC and compensator design based hierarchical sliding mode The results which were previously scattered across various journals and conference proceedings are now presented in a systematic and unified form The book will be of interest to researchers engineers and graduate students in control engineering and mechanical engineering who want to learn the methods and applications of SMC **Control of a crane by means of PLC and fuzzy logic** Katrin Van Dam,Escola Politeca Super.,1995 **Anti-sway Control for Cranes** De Gruyter,2017-11-20 The book introduces anti sway control approaches for double pendulum overhead cranes including control methods theoretical analyses simulation results and source codes of each control design All methods are analyzed and verified by MATLAB Passivity based sliding mode based and Fuzzy logic based control methods are massively discussed This book is suitable for both academic researchers and industrial R D engineers Fuzzy Controller Design Zdenko Kovacic,Stjepan Bogdan,2018-10-08 Fuzzy control methods are critical for meeting the demands of complex nonlinear systems They bestow robust adaptive and self correcting character to complex systems that demand high stability and functionality beyond the capabilities of traditional methods A thorough treatise on the theory of fuzzy logic control is out of place on the design bench

That is why Fuzzy Controller Design Theory and Applications offers laboratory and industry tested algorithms techniques and formulations of real world problems for immediate implementation With surgical precision the authors carefully select the fundamental elements of fuzzy logic control theory necessary to formulate effective and efficient designs The book supplies a springboard of knowledge punctuated with examples worked out in MATLAB SIMULINK from which newcomers to the field can dive directly into applications It systematically covers the design of hybrid adaptive and self learning fuzzy control structures along with strategies for fuzzy controller design suitable for on line and off line operation Examples occupy an entire chapter with a section devoted to the simulation of an electro hydraulic servo system The final chapter explores industrial applications with emphasis on techniques for fuzzy controller implementation and different implementation platforms for various applications With proven methods based on more than a decade of experience Fuzzy Controller Design Theory and Applications is a concise guide to the methodology design steps and formulations for effective control solutions

Dynamics and Control of Industrial Cranes Keum-Shik Hong,Umer Hameed Shah,2019-01-30 This book introduces and develops the mathematical models used to describe crane dynamics and explores established and emerging control methods employed for industrial cranes It opens with a general introduction to the design and structure of various crane types including gantry cranes rotary cranes and mobile cranes currently being used for material handling processes Mathematical models describing their dynamics for control purposes are developed via two different modeling approaches lumped mass and distributed parameter models Control strategies applicable to real industrial problems are then discussed including open loop control feedback control boundary control and hybrid control strategies Finally based on the methods covered in the book future research directions are proposed for the advancement of crane technologies This book can be used by graduate students engineers and researchers in the material handling industryincluding those working in warehouses manufacturing construction sites ship building seaports container terminals nuclear power plants and in offshore engineering

Neuro-Fuzzy Control of Industrial Systems with Actuator Nonlinearities Frank L. Lewis,Javier Campos,Rastko Selmic,2002-01-01 Brings neural networks and fuzzy logic together with dynamical control systems Each chapter presents powerful control approaches for the design of intelligent controllers to compensate for actuator nonlinearities

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Fuzzy Logic Controller for Vehicle-active Suspension System Wei Tek Tan,2001 **Fuzzy Logic Control and Optimization System** ,2012 A control system 300 for optimizing a power plant includes a chemical loop having an input for receiving an input signal 369 and an output for outputting an output signal 367 and a hierarchical fuzzy control system 400

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