

Giuseppe Conte · Claude H. Moog
Anna Maria Perdon



Algebraic Methods for Nonlinear Control Systems

Theory and Applications

2nd Edition



Springer

Algebraic Methods For Nonlinear Control Systems Communications And Control Engineering

Katrin Zwirgmaier



Algebraic Methods For Nonlinear Control Systems Communications And Control Engineering:

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Algebraic Methods for Nonlinear Control Systems Giuseppe Conte, Claude H. Moog, Anna Maria Perdon, 2007-01-19

A self contained introduction to algebraic control for nonlinear systems suitable for researchers and graduate students Algebraic Methods for Nonlinear Control Systems develops a linear algebraic alternative to the usual differential geometric approach to nonlinear control using vector spaces over suitable fields of nonlinear functions It describes a range of results some of which can be derived using differential geometry but many of which cannot They include classical and generalized realization in the nonlinear context accessibility and observability recast for the linear algebraic setting discussion and solution of basic feedback problems results for dynamic and static state and output feedback Dynamic feedback and realization are shown to be dealt with and solved much more easily in the algebraic framework The second edition has been completely revised with new text examples and exercises it is divided into two parts necessary methodology and applications to control problems **Nonlinear Control Systems II** Alberto Isidori, 1999-09-22 This eagerly awaited follow up to Nonlinear Control Systems incorporates recent advances in the design of feedback laws for the purpose of globally stabilizing nonlinear systems via state or output feedback The author is one of the most prominent researchers in the field

Nonlinear Control Systems Alberto Isidori, 2013-04-17 The purpose of this book is to present a self contained description of the fundamentals of the theory of nonlinear control systems with special emphasis on the differential geometric approach The book is intended as a graduate text as well as a reference to scientists and engineers involved in the analysis and design of feedback systems The first version of this book was written in 1983 while I was teaching at the Department of Systems Science and Mathematics at Washington University in St Louis This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana Champaign in 1987 at the Carl Cranz Gesellschaft in Oberpfaffenhofen in 1987 at the University of California in Berkeley in 1988 In addition to a major rearrangement of the last two Chapters of the first version this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985 **Observer Design**

for Nonlinear Dynamical Systems Driss Boutat, Gang Zheng, 2021-07-02 This book presents a differential geometric method for designing nonlinear observers for multiple types of nonlinear systems including single and multiple outputs fully and partially observable systems and regular and singular dynamical systems It is an exposition of achievements in nonlinear observer normal forms The book begins by discussing linear systems introducing the concept of observability and observer design and then explains the difficulty of those problems for nonlinear systems After providing foundational information on the differential geometric method the text shows how to use the method to address observer design problems It presents methods for a variety of systems The authors employ worked examples to illustrate the ideas presented Observer Design for

Nonlinear Dynamical Systems will be of interest to researchers graduate students and industrial professionals working with control of mechanical and dynamical systems

Symmetries and Semi-invariants in the Analysis of Nonlinear Systems Laura Menini, Antonio Tornambè, 2011-05-06 This book details the analysis of continuous and discrete time dynamical systems described by differential and difference equations respectively Differential geometry provides the tools for this such as first integrals or orbital symmetries together with normal forms of vector fields and of maps A crucial point of the analysis is linearization by state immersion The theory is developed for general nonlinear systems and specialized for the class of Hamiltonian systems By using the strong geometric structure of Hamiltonian systems the results proposed are stated in a different less complex and more easily comprehensible manner They are applied to physically motivated systems to demonstrate how much insight into known properties is gained using these techniques Various control systems applications of the techniques are characterized including computation of the flow of nonlinear systems computation of semi invariants computation of Lyapunov functions for stability analysis and observer design

Nonlinear Control Systems Design 1989 A. Isidori, 2014-05-23 In the last two decades the development of specific methodologies for the control of systems described by nonlinear mathematical models has attracted an ever increasing interest New breakthroughs have occurred which have aided the design of nonlinear control systems However there are still limitations which must be understood some of which were addressed at the IFAC Symposium in Capri The emphasis was on the methodological developments although a number of the papers were concerned with the presentation of applications of nonlinear design philosophies to actual control problems in chemical electrical and mechanical engineering

Nonlinear Control Systems II Alberto Isidori, 2012-10-21 This eagerly awaited follow up to Nonlinear Control Systems incorporates recent advances in the design of feedback laws for the purpose of globally stabilizing nonlinear systems via state or output feedback The author is one of the most prominent researchers in the field

Nonholonomic Mechanics and Control A.M. Bloch, 2008-02-03 Our goal in this book is to explore some of the connections between control theory and geometric mechanics that is we link control theory with a geometric view of classical mechanics in both its Lagrangian and Hamiltonian formulations and in particular with the theory of mechanical systems subject to motion constraints This synthesis of topics is appropriate since there is a particularly rich connection between mechanics and nonlinear control theory While an introduction to many important aspects of the mechanics of nonholonomically constrained systems may be found in such sources as the monograph of Neimark and Fufaev 1972 the geometric view as well as the control theory of such systems remains largely scattered through various research journals Our aim is to provide a unified treatment of nonlinear control theory and constrained mechanical systems that will incorporate material that has not yet made its way into texts and monographs

Mechanics has traditionally described the behavior of free and interacting particles and bodies the interaction being described by potential forces It encompasses the Lagrangian and Hamiltonian pictures and in its modern form relies heavily on the tools of

differential geometry see for example Abraham and Marsden 1978 and Arnold 1989 From our own point of view our papers Bloch Krishnaprasad Marsden and Murray 1996 Bloch and Crouch 1995 and Baillieul 1998 have been particularly influential in the formulations presented in this book Control Theory and Nonholonomic Systems Control theory is the theory of prescribing motion for dynamical systems rather than describing their observed behavior

Dissipative Systems Analysis and Control Bernard Brogliato, Rogelio Lozano, Bernhard Maschke, Olav Egeland, 2019-07-03 The third edition of the now standard Dissipative Systems Analysis and Control presents a revised and expanded treatment of dissipative systems theory constituting a self contained advanced introduction for graduate students researchers and practising engineers It examines linear nonlinear and nonsmooth systems with many examples in each chapter occasional infinite dimensional examples are also included Throughout emphasis is placed on the use of the dissipative properties of a system for the design of stable and robust feedback control laws or state observers The theory is substantiated by experimental results and by reference to its application in illustrative physical cases Lagrangian systems passivity based and adaptive controllers are covered thoroughly The third edition is substantially updated to accommodate new material within the existing chapter structure The additions include the introduction of negative imaginary transfer functions the design of stable state observers that use passivity as a tool for their stability analysis a new section on robust set valued control of uncertain Lagrangian systems extended section on discrete time systems especially the preservation of dissipativity after discretization a thorough treatment of nonsmooth set valued Lur e systems well posedness and stability an extended chapter on the Kalman Yakubovich Popov Lemma and over 1000 references

L2 - Gain and Passivity Techniques in Nonlinear Control Arjan van der Schaft, 2012-12-06 With respect to the first edition as Volume 218 in the Lecture Notes in Control and Information Sciences series the basic idea of the second edition has remained the same to provide a compact presentation of some basic ideas in the classical theory of input output and closed loop stability together with a choice of contributions to the recent theory of nonlinear robust and H_∞ control and passivity based control Nevertheless some parts of the book have been thoroughly revised and or expanded in order to have a more balanced presentation of the theory and to include some of the new developments which have been taken place since the appearance of the first edition I soon realized however that it is not possible to give a broad exposition of the existing literature in this area without affecting the spirit of the book which is precisely aimed at a compact presentation So as a result the second edition still reflects very much my personal taste and research interests I trust that others will write books emphasizing different aspects Major changes with respect to the first edition are the following A new section has been added in Chapter 2 relating L_2 gain and passivity via scattering emphasizing a coordinate free geometric treatment The section on stability in Chapter 3 has been thoroughly expanded also incorporating some recent results presented in [182]

Nonlinear Control Systems G. Conte, C.H. Moog, A.M. Perdon, 2014-03-12 This book provides a unique and alternative approach to the study of nonlinear control systems with

applications The approach presented is based on the use of algebraic methods which are intrinsically linear rather than differential geometric methods which are more commonly found in other reference works on the subject This allows the exposition to remain simple from a mathematical point of view and accessible for everyone who has a good understanding of linear control theory The book is divided into the following three parts Part 1 is devoted to mathematical preliminaries and to the development of tools and methods for system analysis Part 2 is concerned with solving specific control problems including disturbance decoupling non interactive control model matching and feedback linearization problems Part 3 introduces differential algebraic notions and discusses their applications to nonlinear control and system theory With numerous examples used to illustrate theoretical results this self contained and comprehensive volume will be of interest to all those who have a good basic knowledge of standard linear control systems **Mathematical Reviews** ,2007

Proceedings of International Conference on Advances in Information and Communication Engineering , *Advanced Control Methods for Industrial Processes* Pablo A. López-Pérez,Omar Jacobo Santos Sánchez,Liliam Rodríguez Guerrero,Patricio Ordaz,2025-03-20 A detailed introduction to mathematical models for new and established control engineers Control engineering is a system that helps us understand electrical physical chemical and biochemical systems through the use of mathematical modeling using inputs outputs and simulations These experimental platforms are implemented in most systems of modern advanced control engineering Advanced Control Methods for Industrial Processes provides a solid grounding in traditional control techniques It emphasizes practical application methods alongside the underlying theory and core instrumentation Each chapter discusses the full profile of the technology covered from the field layer and control layer to its implementation It also includes the interfaces for advanced control systems between controllers and systems theory between different layers and between operators systems Through an emphasis on the practical issues of components devices and hardware circuits the book offers working principles and operation mechanisms that allow an engineer to put theory into practice for the advanced control techniques Advanced Control Methods for Industrial Processes readers will also find A practical overview on advanced control methods applied to real time and in silico systems Specific parameters install procedures calibration and configuration methodologies necessary to conduct the relevant models Clear insights into the necessary mathematical models Tutorial material to facilitate the understanding of core concepts Advanced Control Methods for Industrial Processes is an ideal companion for process engineers control engineers and chemists in industry **Encyclopaedia of Mathematics** M. Hazewinkel,2013-12-01 *Scientific and Technical Aerospace Reports* ,1995 Feedback Stabilization of Controlled Dynamical Systems Nicolas Petit,2017-03-23 This book is a tribute to Professor Laurent Praly and follows on from a workshop celebrating the occasion of his 60th birthday It presents new and unified visions of the numerous problems that Laurent Praly has worked on in his prolific career adaptive control output feedback and observers stability and stabilization His main contributions are the central topic of this book The book collects

contributions written by prominent international experts in the control community addressing a rich variety of topics emerging ideas advanced applications and theoretical concepts Organized in three sections the first section covers the field of adaptive control where Laurent Praly started his career The second section focuses on stabilization and output feedback which is also the topic of the second half of his career Lastly the third section presents the emerging research that will form Laurent Praly s scientific legacy **Graduate Announcement** University of Michigan--Dearborn,1984 Air Force Research Resumés ,

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