

Sensorless position estimation of Permanent-Magnet Synchronous Motors using a saturation model

Al Kasseem Jebai, François Malrait, Philippe Martin and Pierre Rouchon

Abstract—Sensorless control of Permanent-Magnet Synchronous Motors (PMSM) at low velocity remains a challenging task. A new well-established method consists in injecting a high-frequency signal and use the rotor saliency, both geometric and magnetic-saturation induced. This paper proposes a clear and original analysis based on second-order averaging of how to recover the position information from signal injection; this analysis blends well with a general model of magnetic saturation. It also proposes a simple parametric model of the saturated PMSM, based on an energy function which simply encompasses saturation and cross-saturation effects. Experimental results on a surface-mounted PMSM and an interior magnet PMSM illustrate the relevance of the approach.

Index Terms—Permanent-magnet synchronous motor, sensorless position estimation, signal injection, magnetic saturation, energy-based modeling, averaging.

I. INTRODUCTION

PERMANENT-Magnet Synchronous Motors (PMSM) are widely used in industry. In the so-called “sensorless” mode of operation, the rotor position and velocity are not measured and the control law must make do with only current measurements. While sensorless control at medium to high velocities is well understood, with many reported control schemes and industrial products, sensorless control at low velocity remains a challenging task. The reason is that observability degenerates at zero velocity, causing a serious problem in the necessary rotor position estimation.

A new well-established method to overcome this problem is to add some persistent excitation by injecting a high-frequency signal [1] and use the rotor saliency, whether geometric for Interior Permanent-Magnet machines or induced by main flux saturation for Surface Permanent-Magnet machines [2]–[10]. Signal injection is moreover considered as a standard building block in hybrid control schemes for complete drives operating from zero to full speed [11]–[15].

However to get a good position estimation under high-load condition it is important to take cross-saturation into account [16]–[26]. It is thus necessary to rely on a model of the saturated PMSM adapted to control purposes, i.e. rich enough to capture in particular cross-saturation but also simple enough to be used in real-time and to be easily identified in the field; see [27]–[32] for references more or less in this spirit.

The contribution of this paper, which builds on the preliminary work [33], is twofold: on the one hand it proposes a clear

and original analysis based on second-order averaging of how to recover the position information from signal injection; this analysis can accommodate to any form of injected signals, e.g. square signals as in [34], and blends well with a general model of magnetic saturation including cross-saturation. On the other hand a simple parametric model of the saturated PMSM, well-adapted to control purposes, is introduced; it is based on an energy function which simply encompasses saturation and cross-saturation effects.

The paper runs as follows: section II presents the saturation model. In section III position estimation by signal injection is studied thanks to second-order averaging. Section IV is devoted to the estimation of the parameters entering the saturation model using once again signal injection and averaging. Finally section IV-C experimentally demonstrates on two kinds of motors (with interior magnets and surface-mounted magnets) the relevance of the approach and the necessity of considering saturation to correctly estimate the position.

II. AN ENERGY-BASED MODEL OF THE SATURATED PMSM

A. Notations

In the sequel we denote by $x_{ij} := (x_i, x_j)^T$ the vector made from the real numbers x_i and x_j , where ij can be dq , $\alpha\beta$ or $\gamma\delta$. We also define the matrices

$$M_\mu := \begin{pmatrix} \cos \mu & -\sin \mu \\ \sin \mu & \cos \mu \end{pmatrix} \quad \text{and} \quad K := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix},$$

and we have the useful relation

$$\frac{dM_\mu}{d\mu} = KM_\mu = M_\mu K.$$

B. Energy-based model

The model of a two-axis PMSM expressed in the synchronous $d-q$ frame reads

$$\frac{d\phi_{dq}}{dt} = u_{dq} - R i_{dq} - \omega K(\phi_{dq} + \phi_m) \quad (1)$$

$$\frac{J}{n^2} \frac{d\omega}{dt} = \frac{3}{2} i_{dq}^T K(\phi_{dq} + \phi_m) - \frac{\tau_L}{n} \quad (2)$$

$$\frac{d\theta}{dt} = \omega, \quad (3)$$

with ϕ_{dq} flux linkage due to the current; $\phi_m := (\lambda, 0)^T$ constant flux linkage due to the permanent magnet; u_{dq} impressed voltage and i_{dq} stator current; ω and θ rotor (electrical) speed and position; R stator resistance; n number of pole pairs; J inertia moment and τ_L load torque. The physically impressed voltages are $u_{\alpha\beta} := M_\mu u_{dq}$ while the physically measurable

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Sensorless Position Estimation Of Permanent Magnet:

Sensorless Position Estimation in Sinusoidal Permanent Magnet Synchronous Motor Deepak Shivaram Shet,1998 **Real Time Implementation of Sensorless Position Estimation in a Permanent Magnet Synchronous Motor Using DSP TMS320C24X** Rohit Khetarpal,2003 **Position Sensorless Control Techniques for Permanent Magnet Synchronous Machine Drives** Gaolin Wang,Guoqiang Zhang,Dianguo Xu,2019-11-15 The book focuses on position sensorless control for PMSM drives addressing both basic principles and experimental evaluation It provides an in depth study on a number of major topics such as model based sensorless control saliency based sensorless control position estimation error ripple elimination and acoustic noise reduction Offering a comprehensive and systematic overview of position sensorless control and practical issues it is particularly suitable for readers interested in the sensorless control techniques for PMSM drives The book is also a valuable resource for researchers engineers and graduate students in fields of ac motor drives and sensorless control *The Proceedings of the 9th Frontier Academic Forum of Electrical Engineering* Weiming Ma,Mingzhe Rong,Fei Yang,Wenfeng Liu,Shuhong Wang,Gengfeng Li,2021-04-21 This book includes the original peer reviewed research papers from the 9th Frontier Academic Forum of Electrical Engineering FAFEE 2020 held in Xi an China in August 2020 It gathers the latest research innovations and applications in the fields of Electrical Engineering The topics it covers including electrical materials and equipment electrical energy storage and device power electronics and drives new energy electric power system equipment IntelliSense and intelligent equipment biological electromagnetism and its applications and insulation and discharge computation for power equipment Given its scope the book benefits all researchers engineers and graduate students who want to learn about cutting edge advances in Electrical Engineering

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and sensorless control Covers inverter sensors vehicle dynamics driving cycles etc not just motor control itself Offers a comparison between BLDC surface PMSM and interior PMSM Discusses how the motor produces torque and is controlled based on consistent mathematical treatments Power Electronics Handbook Muhammad H. Rashid, 2010-07-19 Power electronics which is a rapidly growing area in terms of research and applications uses modern electronics technology to convert electric power from one form to another such as ac dc dc dc dc ac and ac ac with a variable output magnitude and frequency Power electronics has many applications in our every day life such as air conditioners electric cars sub way trains motor drives renewable energy sources and power supplies for computers This book covers all aspects of switching devices converter circuit topologies control techniques analytical methods and some examples of their applications 25% new content Reorganized and revised into 8 sections comprising 43 chapters Coverage of numerous applications including uninterruptable power supplies and automotive electrical systems New content in power generation and distribution including solar power fuel cells wind turbines and flexible transmission **Power Converters and AC Electrical Drives with Linear Neural Networks** Maurizio Cirrincione, Marcello Pucci, Gianpaolo Vitale, 2012-05-07 The first book of its kind Power Converters and AC Electrical Drives with Linear Neural Networks systematically explores the application of neural networks in the field of power electronics with particular emphasis on the sensorless control of AC drives It presents the classical theory based on space vectors in identification discusses control of electrical drives and power converters and examines improvements that can be attained when using linear neural networks The book integrates power electronics and electrical drives with artificial neural networks ANN Organized into four parts it first deals with voltage source inverters and their control It then covers AC electrical drive control focusing on induction and permanent magnet synchronous motor drives The third part examines theoretical aspects of linear neural networks particularly the neural EXIN family The fourth part highlights original applications in electrical drives and power quality ranging from neural based parameter estimation and sensorless control to distributed generation systems from renewable sources and active power filters Simulation and experimental results are provided to validate the theories Written by experts in the field this state of the art book requires basic knowledge of electrical machines and power electronics as well as some familiarity with control systems signal processing linear algebra and numerical analysis Offering multiple paths through the material the text is suitable for undergraduate and postgraduate students theoreticians practicing engineers and researchers involved in applications of ANNs Vehicle, Mechatronics and Information Technologies X.D. Yu, 2013-08-30 Selected peer reviewed papers from the 2013 International Conference on Vehicle Mechanical Engineering and Information Technology VMEIT 2013 August 17 18 2013 Zhengzhou Henan China **Design Rules for Induction Machine Self-sensing** Ian P. Brown, 2009 **Second International Conference on Power Electronics, Machines, and Drives (PEMD 2004)**, 2004 **Proceedings of the 1995 IEEE IECON: Signal processing and control, Robotics vision and sensors, Emerging technologies, and**

Factory automation ,1995 *IEEE International Symposium on Industrial Electronics Proceedings* ,2004 **ICEMS'2001**
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