

# Model Predictive Control System Design and Implementation Using MATLAB®

# Design And Implementation Of Model Predictive Control

**Haralambos Sarimveis**



## **Design And Implementation Of Model Predictive Control:**

*Model Predictive Control System Design and Implementation Using MATLAB®* Liuping Wang, 2009-02-14 Model Predictive Control System Design and Implementation Using MATLAB proposes methods for design and implementation of MPC systems using basis functions that confer the following advantages continuous and discrete time MPC problems solved in similar design frameworks a parsimonious parametric representation of the control trajectory gives rise to computationally efficient algorithms and better on line performance and a more general discrete time representation of MPC design that becomes identical to the traditional approach for an appropriate choice of parameters After the theoretical presentation coverage is given to three industrial applications The subject of quadratic programming often associated with the core optimization algorithms of MPC is also introduced and explained The technical contents of this book is mainly based on advances in MPC using state space models and basis functions This volume includes numerous analytical examples and problems and MATLAB programs and exercises      Practical Design and Application of Model Predictive Control Nassim Khaled, Bibin Pattel, 2018-05-04 Practical Design and Application of Model Predictive Control is a self learning resource on how to design tune and deploy an MPC using MATLAB and Simulink This reference is one of the most detailed publications on how to design and tune MPC controllers Examples presented range from double Mass spring system ship heading and speed control robustness analysis through Monte Carlo simulations photovoltaic optimal control and energy management of power split and air handling control Readers will also learn how to embed the designed MPC controller in a real time platform such as Arduino The selected problems are nonlinear and challenging and thus serve as an excellent experimental dynamic system to show the reader the capability of MPC The step by step solutions of the problems are thoroughly documented to allow the reader to easily replicate the results Furthermore the MATLAB and Simulink codes for the solutions are available for free download Readers can connect with the authors through the dedicated website which includes additional free resources at [www.practicalmpc.com](http://www.practicalmpc.com) Illustrates how to design tune and deploy MPC for projects in a quick manner Demonstrates a variety of applications that are solved using MATLAB and Simulink Bridges the gap in providing a number of realistic problems with very hands on training Provides MATLAB and Simulink code solutions This includes nonlinear plant models that the reader can use for other projects and research work Presents application problems with solutions to help reinforce the information learned      Design and Implementation of Model Predictive Control Algorithms for Small Satellite Three-axis Stabilization Chen, Xi, 2011      **New Directions on Model Predictive Control** Jinfeng Liu, Helen E Durand, 2019-01-16 This book is a printed edition of the Special Issue New Directions on Model Predictive Control that was published in Mathematics      **UAV Sensors for Environmental Monitoring** Felipe Gonzalez Toro, Antonios Tsourdos, 2018-03-05 This book is a printed edition of the Special Issue UAV Sensors for Environmental Monitoring that was published in Sensors      **Incremental Model Predictive Control System Design and**

**Implementation Using MATLAB/Simulink** Xin Lin, 2013 The integral and model predictive controller MPC drive controlled outputs to their desired targets and this thesis addresses the problem of integral controller incremental and integral MPC when tracking the constant or inconstant references Design and implementation of the MPC under MATLAB Simulink environment are discussed both in incremental and integral form Also one CSTR example is presented to compare the control performances among different integral controller and MPCs

**Model Predictive Control of Wind Energy Conversion Systems** Venkata Yaramasu, Bin Wu, 2016-12-19 Model Predictive Control of Wind Energy Conversion Systems addresses the predictive control strategy that has emerged as a promising digital control tool within the field of power electronics variable speed motor drives and energy conversion systems The authors provide a comprehensive analysis on the model predictive control of power converters employed in a wide variety of variable speed wind energy conversion systems WECS The contents of this book includes an overview of wind energy system configurations power converters for variable speed WECS digital control techniques MPC modeling of power converters and wind generators for MPC design Other topics include the mapping of continuous time models to discrete time models by various exact approximate and quasi exact discretization methods modeling and control of wind turbine grid side two level and multilevel voltage source converters The authors also focus on the MPC of several power converter configurations for full variable speed permanent magnet synchronous generator based WECS squirrel cage induction generator based WECS and semi variable speed doubly fed induction generator based WECS Furthermore this book Analyzes a wide variety of practical WECS illustrating important concepts with case studies simulations and experimental results Provides a step by step design procedure for the development of predictive control schemes for various WECS configurations Describes continuous and discrete time modeling of wind generators and power converters weighting factor selection discretization methods and extrapolation techniques Presents useful material for other power electronic applications such as variable speed motor drives power quality conditioners electric vehicles photovoltaic energy systems distributed generation and high voltage direct current transmission Explores S Function Builder programming in MATLAB environment to implement various MPC strategies through the companion website Reflecting the latest technologies in the field Model Predictive Control of Wind Energy Conversion Systems is a valuable reference for academic researchers practicing engineers and other professionals It can also be used as a textbook for graduate level and advanced undergraduate courses

*Design and Development of Model Predictive Primary Control of Micro Grids* Puvvula Vidyasagar, K. Shanti Swarup, 2023-01-01 This book provides a design and development perspective MPC for micro grid control emphasizing step by step conversion of a nonlinear MPC to linear MPC preserving critical aspects of nonlinear MPC The book discusses centralized and decentralized MPC control algorithms for a generic modern day micro grid consisting of vital essential constituents It starts with the nonlinear MPC formulation for micro grids It also moves towards the linear time invariant and linear time variant approximations of the MPC for micro grid

control The contents also discuss how the application of orthonormal special functions can improve computational complexity of MPC algorithms It also highlights various auxiliary requirements like state estimator disturbance compensator for robustness selective harmonic eliminator for eliminating harmonics in the micro grid etc These additional requirements are crucial for the successful online implementation of the MPC In the end the book shows how a well designed MPC is superior in performance compared to the conventional micro grid primary controllers discussed above The key topics discussed in this book include the detailed modeling of micro grid components operational modes in micro grid and their control objectives conventional micro grid primary controllers the importance of MPC as a micro grid primary controller understanding of MPC operation nonlinear MPC formulation linear approximations of MPC application of special functions in the MPC formulation and other online requirements for the MPC implementation The examples in the book are available both from a calculation point of view and as MATLAB codes This helps the students get acquainted with the subject first and then allows them to implement the subject they learn in software for further understanding and research

*Assessment and Future Directions of Nonlinear Model Predictive Control* Rolf Findeisen, Frank Allgöwer, Lorenz Biegler, 2007-09-08 The past three decades have seen rapid development in the area of model predictive control with respect to both theoretical and application aspects Over these 30 years model predictive control for linear systems has been widely applied especially in the area of process control However today's applications often require driving the process over a wide region and close to the boundaries of operability while satisfying constraints and achieving near optimal performance Consequently the application of linear control methods does not always lead to satisfactory performance and here nonlinear methods must be employed This is one of the reasons why nonlinear model predictive control NMPC has enjoyed significant attention over the past years with a number of recent advances on both the theoretical and application frontier Additionally the widespread availability and steadily increasing power of today's computers as well as the development of specially tailored numerical solution methods for NMPC bring the practical applicability of NMPC within reach even for very fast systems This has led to a series of new exciting developments along with new challenges in the area of NMPC

### **Nonlinear Model Predictive Control**

Frank Allgöwer, Alex Zheng, 2012-12-06 During the past decade model predictive control MPC also referred to as receding horizon control or moving horizon control has become the preferred control strategy for quite a number of industrial processes There have been many significant advances in this area over the past years one of the most important ones being its extension to nonlinear systems This book gives an up to date assessment of the current state of the art in the new field of nonlinear model predictive control NMPC The main topic areas that appear to be of central importance for NMPC are covered namely receding horizon control theory modeling for NMPC computational aspects of on line optimization and application issues The book consists of selected papers presented at the International Symposium on Nonlinear Model Predictive Control

Assessment and Future Directions which took place from June 3 to 5 1998 in Ascona Switzerland The book is geared towards

researchers and practitioners in the area of control engineering and control theory It is also suited for postgraduate students as the book contains several overview articles that give a tutorial introduction into the various aspects of nonlinear model predictive control including systems theory computations modeling and applications

*Economic Model Predictive Control* Matthew Ellis, Jinfeng Liu, Panagiotis D. Christofides, 2016-07-27 This book presents general methods for the design of economic model predictive control EMPC systems for broad classes of nonlinear systems that address key theoretical and practical considerations including recursive feasibility closed loop stability closed loop performance and computational efficiency Specifically the book proposes Lyapunov based EMPC methods for nonlinear systems two tier EMPC architectures that are highly computationally efficient and EMPC schemes handling explicitly uncertainty time varying cost functions time delays and multiple time scale dynamics The proposed methods employ a variety of tools ranging from nonlinear systems analysis through Lyapunov based control techniques to nonlinear dynamic optimization The applicability and performance of the proposed methods are demonstrated through a number of chemical process examples The book presents state of the art methods for the design of economic model predictive control systems for chemical processes In addition to being mathematically rigorous these methods accommodate key practical issues for example direct optimization of process economics time varying economic cost functions and computational efficiency Numerous comments and remarks providing fundamental understanding of the merging of process economics and feedback control into a single framework are included A control engineer can easily tailor the many detailed examples of industrial relevance given within the text to a specific application The authors present a rich collection of new research topics and references to significant recent work making *Economic Model Predictive Control* an important source of information and inspiration for academics and graduate students researching the area and for process engineers interested in applying its ideas

*Advanced Model Predictive Control for Autonomous Marine Vehicles* Yang Shi, Chao Shen, Henglai Wei, Kunwu Zhang, 2023-02-13 This book provides a comprehensive overview of marine control system design related to underwater robotics applications In particular it presents novel optimization based model predictive control strategies to solve control problems appearing in autonomous underwater vehicle applications These novel approaches bring unique features such as constraint handling prioritization between multiple design objectives optimal control performance and robustness against disturbances and uncertainties into the control system design They therefore form a more general framework to design marine control systems and can be widely applied *Advanced Model Predictive Control for Autonomous Marine Vehicles* balances theoretical rigor providing thorough analysis and developing provably correct design conditions and application perspectives addressing practical system constraints and implementation issues Starting with a fixed point positioning problem for a single vehicle and progressing to the trajectory tracking and path following problem of the vehicle and then to the coordination control of a large scale multi robot team this book addresses the motion control problems increasing their level of challenge step by step At each step

related subproblems such as path planning thrust allocation collision avoidance and time constraints for real time implementation are also discussed with solutions In each chapter of this book compact and illustrative examples are provided to demonstrate the design and implementation procedures As a result this book is useful for both theoretical study and practical engineering design and the tools provided in the book are readily applicable for real world implementation

*Uncertainty in Mechanical Engineering* Holger Hanselka, Peter Groche, Roland Platz, 2011-09-27 Selected peer reviewed papers from the 1st International Conference on Uncertainty in Mechanical Engineering ICUME 2011 November 14 15 2011 Darmstadt Germany

Model Predictive Control - Theory and Applications Constantin Voloşencu, 2023-07-12 The book presents some recent specialized theoretical and practical works in the field of process control based on the model predictive control MPC method It includes seven chapters that present studies on the application of MPC in various technical processes such as the atmospheric plasma spray process permanent magnet synchronous motors monitoring of the pose of a walking person monitoring of the heat treatment process of raw materials discrete event processes control of passenger vehicles and natural gas sweetening processes Chapters include examples and case studies from researchers in the field This volume provides readers with new solutions and answers to questions related to the emerging applications of MPC and their implementation

**Model Predictive Control** Aris Daniilidis, Lars Grüne, Josef Haunschmied, Gernot Tragler, 2025-06-07 The book explores the field of model predictive control MPC It reports on the latest developments in MPC current applications and presents various subfields of MPC The book features topics such as uncertain and stochastic MPC variants learning and neural network approaches easy to use numerical implementations as well as multi agent systems and scheduling and coordination tasks While MPC is rooted in engineering science this book illustrates the potential of using MPC theory and methods in non engineering sciences and applications such as economics finance and environmental sciences

**Advanced Model Predictive Control** Tao Zheng, 2011-07-05 Model Predictive Control MPC refers to a class of control algorithms in which a dynamic process model is used to predict and optimize process performance From lower request of modeling accuracy and robustness to complicated process plants MPC has been widely accepted in many practical fields As the guide for researchers and engineers all over the world concerned with the latest developments of MPC the purpose of Advanced Model Predictive Control is to show the readers the recent achievements in this area The first part of this exciting book will help you comprehend the frontiers in theoretical research of MPC such as Fast MPC Nonlinear MPC Distributed MPC Multi Dimensional MPC and Fuzzy Neural MPC In the second part several excellent applications of MPC in modern industry are proposed and efficient commercial software for MPC is introduced Because of its special industrial origin we believe that MPC will remain energetic in the future

*Advances in Process Control with Real Applications* Ch. Venkateswarlu, 2025-06-18 *Advances in Process Control with Real Applications* presents various advanced controllers including the formulation design and implementation of various advanced control strategies for a wide variety of processes

These strategies include generalized predictive control with and without constraints linear and nonlinear model predictive control dynamic matrix control nonlinear control such as generic model control globally linearizing control and nonlinear internal model control optimal and optimizing control inferential control intelligent control based on fuzzy reasoning and neural networks and controllers based on stochastic and evolutionary optimization This book will be highly beneficial to students researchers and industry professionals working in process design process monitoring process systems engineering process operations and control and related areas Describes various advanced controllers for the control of complex nonlinear processes Provides the fundamentals algorithms approaches control strategies and implementation procedures systematically Highlights the significance and importance of advanced process control with many real applications

**Learning-based Model Predictive Control with closed-loop guarantees** Raffaele Soloperto, 2023-11-13 The performance of model predictive control MPC largely depends on the accuracy of the prediction model and of the constraints the system is subject to However obtaining an accurate knowledge of these elements might be expensive in terms of money and resources if at all possible In this thesis we develop novel learning based MPC frameworks that actively incentivize learning of the underlying system dynamics and of the constraints while ensuring recursive feasibility constraint satisfaction and performance bounds for the closed loop In the first part we focus on the case of inaccurate models and analyze learning based MPC schemes that include in addition to the primary cost a learning cost that aims at generating informative data by inducing excitation in the system In particular we first propose a nonlinear MPC framework that ensures desired performance bounds for the resulting closed loop and then we focus on linear systems subject to uncertain parameters and noisy output measurements In order to ensure that the desired learning phase occurs in closed loop operations we then propose an MPC framework that is able to guarantee closed loop learning of the controlled system In the last part of the thesis we investigate the scenario where the system is known but evolves in a partially unknown environment In such a setup we focus on a learning based MPC scheme that incentivizes safe exploration if and only if this might yield to a performance improvement

[Handbook of Model Predictive Control](#) Saša V. Raković, William S. Levine, 2018-09-01 Recent developments in model predictive control promise remarkable opportunities for designing multi input multi output control systems and improving the control of single input single output systems This volume provides a definitive survey of the latest model predictive control methods available to engineers and scientists today The initial set of chapters present various methods for managing uncertainty in systems including stochastic model predictive control With the advent of affordable and fast computation control engineers now need to think about using computationally intensive controls so the second part of this book addresses the solution of optimization problems in real time for model predictive control The theory and applications of control theory often influence each other so the last section of Handbook of Model Predictive Control rounds out the book with representative applications to automobiles healthcare robotics and finance The chapters in this volume will be useful to

working engineers scientists and mathematicians as well as students and faculty interested in the progression of control theory Future developments in MPC will no doubt build from concepts demonstrated in this book and anyone with an interest in MPC will find fruitful information and suggestions for additional reading

**Robust Model Predictive Control for Large-Scale Manufacturing Systems subject to Uncertainties** Jens Tonne, 2018-01-19 Large scale manufacturing systems are often run with constant process parameters although continuous and abrupt disturbances influence the process To reduce quality variations and scrap a closed loop control of the process variables becomes indispensable In this thesis a modeling and control framework for multistage manufacturing systems is developed in which the systems are subject to abrupt faults such as component defects and continuous disturbances In this context three main topics are considered the development of a modeling framework the design of robust distributed controllers and the application of both to the models of a real hot stamping line The focus of all topics is on the control of the product properties considering the available knowledge of faults and disturbances

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