

#### Design of Closed Loop Electro Mechanical Actuation System

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ABSTRACT: An Actuator is basically a position serve control system used in industries and vehicles. A rotary electric mechanical actuation system is an angular positioning system used in acrospace applications such as control of rudder and afterons of serve planes and control of control surfaces, jet vanes, etc. This position loop system is to steen the vehicle to move in required direction.

A serve controller is a driver to accurately control the position of the actuation system by getting the command signals from the on-board computer of the vehicle. It involves a class of DSP controller optimized for digital motor motion control and power conversion applications.

In this thesis, Closed loop. Rotary Electro Mechanical Actuating system is designed for the derived specifications by using the CAD software UNIGRAPHICS, and simulated the design with the help of FEA software ANSTS and MATLAB.

KEYWORDS: Actuator, ANSYS, CAD, DSP controller, UNIGRAPHICS.

#### I. INTRODUCTION

This document covers the description, design, inputs and specifications of the Actuation System for nerodynamic control of an Aero-vehicle. The document also describes the actuator specifications, mechanical components, BLDC motor, position sensor and the control system including simulation.

#### 1. L. Accountor-

An actuator is a mechanism that converts energy into motion. It can also be used to apply a force. An actuator typically is a mechanical device that takes energy, usually created by air, electricity, or liquid, and converts that into some kind of motion. That motion can be anything from blocking to clamping to ejecting. Actuators are typically used in manufacturing or industrial applications and may be used in things like moters, pumps, switches, and valves. The most common type of actuator is powered by air — the pneumatic cylinder, also known as the aircylinder. Air cylinders are air-tight cylinders, typically made from metal, that use the energy of compressed air to move a piston. Air cylinders are most commonly used in manufacturing and assembly processes. Grippers, which are used in robotics, use actuators driven by compressed air to work much like human fingers. Actuators can also be powered by electricity or hydraulics. Much like there are air cylinders, there are also electric cylinders and hydraulic cylinders where the cylinder converts electricity or hydraulics into motion. Hydraulic cylinders are often used in certain types of vehicles.

Many actuators have more than one type of power source. Solenoid valves, for example, can be powered by air and electricity. Electricity powers the solenoid, and the solenoid, powered by air actuates the valve. Alternatively, the solenoid can be powered by hydraulies and electricity. Actuators can create a linear motion, rotary motion, or oscillatory motion. That is, they can create motion in one direction, in a circular motion, or in opposite directions at regular intervals. Hydraulie and air cylinders can be classified as single acting, meaning that the energy source causes movement in one direction and a spring is used for the other direction. Alternatively, these cylinders can be double acting cylinders, meaning the energy is used in two directions. While actuators are typically discussed in terms of mechanical implements, muscles are sometimes given as an example of an actuator. Energy (e.g., created by eating carbohydrates) is converted by the muscle (i.e., the actuator) into motion (e.g., kicking a ball).

# <u>Design Of Closed Loop Electro Mechanical Actuation</u> <u>System</u>

**M** Carnoy

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