



Autonomous Navigation With Radar

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Autonomous Navigation With Radar:

Robotic Navigation and Mapping with Radar Martin Adams, Martin David Adams, 2012 A practical treatment of short range radar processing for reliable object detection at ground level *Radar and Sonar Imaging and Processing* Andrzej Stateczny, Krzysztof Kulpa, Witold Kazimierski, 2021-01-22 The Special Issue Radar and Sonar Imaging Processing is a collection of 21 articles exploring many topics related to remote sensing with radar and sonar sensors In this editorial we present short introductions of the published articles The series of articles in this SI deal with a broad profile of aspects of the use of radar and sonar images in line with the latest scientific trends while making use of the latest developments in science including artificial intelligence It can be said that both radar and sonar imaging and processing still remain a hot topic and much research in this area is being conducted worldwide New techniques and methods for extracting information from radar and sonar sensors and data have been proposed and verified Some of these will stimulate further research while others have reached maturity and can be considered for industrial implementation and development **Precision FMCW Short-Range Radar for Industrial Applications** Boris A. Atayants, Viacheslav M. Davydochkin, Victor V. Ezerskiy, Valery S. Parshin, Sergey M. Smolskiy, 2014-04-01 This book describes methods for making accurate radar measurements of short distances in applications where physical contact with materials is impractical Sources of error are identified and methods of reducing these errors are described Practical test procedures for measuring instruments are also provided Much of the book is dedicated to providing radar engineers with practical applications detailing the conditions equipment and approach of experimental estimation With the help of computer simulation the achievable advantages in accuracy of radar range measurement with various approaches are revealed and quantitatively estimated Readers are also provided with methods of random process theory and mathematical statistics along with functional analysis and optimization **Field and Service Robotics** Alexander Zelinsky, 2012-12-06 Joe Engelberger the pioneer of the robotics industry wrote in his 1989 book *Robotics in Service* that the inspiration to write his book came as a reaction to an industry sponsored forecast study of robot applications which predicted that in 1995 applications of robotics outside factories the traditional domain of industrial robots would amount to less than 1% of total sales Engelberger believed that this forecast was very wrong and instead predicted that the non industrial class of robot applications would become the largest class Engelbergers prediction has yet to come to pass However he did correctly foresee the growth in non traditional applications of robots Robots are now beginning to march from the factories and into field and service applications This book presents a selection of papers from the first major international conference dedicated to field and service applications of robotics This selection includes papers from the leading research laboratories in the world together with papers from companies that are building and selling new and innovative robotic technology It describes interesting aspects of robots in the field ranging from mining agriculture construction cargo handling subsea operations removal of landmines to terrestrial exploration It also covers a diverse range

of service applications such as cleaning propagating plants and aiding the elderly and handicapped and gives considerable attention to the technology required to realise robust reliable and safe robots

Sparse Arrays for Radar, Sonar, and Communications Moeness G. Amin, 2024-01-11 Specialized resource providing detailed coverage of recent advances in theory and applications of sparse arrays Sparse Arrays for Radar Sonar and Communications discusses various design approaches of sparse arrays including those seeking to increase the corresponding one dimensional and two dimensional virtual array apertures as well as others that configure the arrays based on solutions of constrained minimization problems The latter includes statistical bounds and signal to interference and noise ratio in this respect the book utilizes the recent strides made in convex optimizations and machine learning for sparse array configurability in both fixed and dynamic environments Similar ideas are presented for sparse array waveform design The book also discusses the role of sparse arrays in improving target detection and resolution in radar improving channel capacity in massive MIMO and improving underwater target localization in sonar It covers different sparse array topologies and provides various approaches that deliver the optimum and semi optimum sparse array transceivers Edited by a world leading expert in Radar and Signal Processing and contributed to by world class researchers in their respective fields Sparse Arrays for Radar Sonar and Communications covers topics including Utilizing sparse arrays in emerging technologies and showing their offerings in various sensing and communications applications Applying sparse arrays to different environments and obtain superior performances over conventional uniform arrays Solving the localization beamforming and direction finding problems using non uniform array structures for narrowband and wideband signals Designing sparse array structures for both stationary and moving platforms that produce physical and synthesized array apertures Using deep neural networks that learn the underlying complex nonlinear model and output the sparse array configuration using representations of the input data spatio temporal observations Solving for optimum sparse array configurations and beamforming coefficients in sensing using iterative convex optimization methods Providing complete coverage of the recent considerable progress in sparse array design and configurations Sparse Arrays for Radar Sonar and Communications is an essential resource on the subject for graduate students and engineers pursuing research and applications in the broad areas of active passive sensing and communications

Active Sensors For Local Planning In Mobile Robotics Penelope Probert Smith, 2001-12-05 This book describes recent work on active sensors for mobile robots An active sensor interacts with its surroundings to supply data on demand for a particular function gathering and abstracting information according to need rather than acting as a generic data gatherer Details of the physical operation are hidden The book deals mainly with active range sensors which provide rapid information for local planning describing extraction of two dimensional features such as lines corners and cylinders to reconstruct a plan of a building It is structured according to the physical principles of the sensors since to a large extent these determine the function of the sensors and the methods of processing Recent work using sonar optoelectronic sensors and radar is described

Sections on vision and on sensor management develop the idea of software adaptation for efficient operation in a changing environment Advanced Concepts for Intelligent Vision Systems Wilfried Philips,Dan Popescu,Paul Scheunders,2009-09-30 This book constitutes the refereed proceedings of the 11th International Conference on Advanced Concepts for Intelligent Vision Systems ACIVS 2009 held in Bordeaux France in September October 2009 The 43 revised full papers and 25 posters presented were carefully reviewed and selected from 115 submissions The papers are organized in topical sections on technovision fundamental mathematical techniques image processing coding and filtering image and video analysis computer vision tracking color multispectral and special purpose imaging medical imaging and biometrics Synchronous Impulse Reconstruction (SIRE) Radar Sensor for Autonomous Navigation ,2006 The Army Research Laboratory ARL has designed and fabricated an impulse based ultra wideband UWB imaging radar to examine the utility of using a foliage penetrating radar with other sensors to support autonomous navigation in robotic vehicles This radar would also have application in mine detection and through the wall sensing This proof of concept radar system employs a physical array of 16 receive antennas to provide the necessary aperture for sufficient crossrange resolution in the forward looking geometry used in a robotic mission Each antenna feeds a base band receiver digitizer that integrates the data from a number of radar pulses before passing it on to the personal computer PC based operator s console and display The innovative ARL receiver design uses commercially available integrated circuits to provide a low cost lightweight digitizing scheme with an effective sampling rate of approximately 8 GHz The design is extensible to allow for growth in the number of channels used and improvements in integrated circuit performance to eventually meet the expected unmanned ground vehicle combat pace Using modules based on commercial off the shelf COTS components allows for continued expansion of capabilities of the system based on increasing capabilities of these components **Technology of Lunar Soft Lander** Deng-Yun Yu,Ze-Zhou Sun,He Zhang,2021-03-25 This book provides systematic descriptions of design methods typical techniques and validation methods for lunar soft landers covering their environmental design system design sub system design assembly testing and ground test validation based on the Chang e 3 mission Offering readers a comprehensive systematic and in depth introduction to the technologies used in China s lunar soft landers it presents detailed information on the design process for Chang e 3 including methods and techniques that will be invaluable in future extraterrestrial soft lander design As such the book offers a unique reference guide for all researchers and professionals working on deep space missions around the globe *Mobile Robots for Digital Farming* Redmond R. Shamshiri,Ibrahim A. Hameed,2024-09-09 This book provides a complete and comprehensive reference for agricultural mobile robots covering all aspects of the design process from sensing and perceiving to planning and acting for practical farming applications Mobile Robots for Digital Farming explores topics such as Robot Operating Systems ROS dynamic simulation artificial intelligence image processing and machine learning Additionally it features multiple case studies from funded projects and real field trials This book will be useful for professors and academics in

various engineering disciplines mechanical robotics control electrical computer and agricultural graduate and undergraduate students farmers commercial growers startups private companies consultancy agencies equipment suppliers and agricultural policymakers

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Aerospace Sensors Alexander Nebylov,2012-11-20 Modern air and space craft demand a huge variety of sensing elements for detecting and controlling their behavior and operation These sensors often differ significantly from those designed for applications in automobile ship railway and other forms of transportation and those used in industrial chemical medical and other areas This book offers insight into an appropriate selection of these sensors and describes their principles of operation design and achievable performance along with particulars of their construction Drawn from the activities of the International Federation of Automatic Control IFAC especially its Aerospace Technical Committee the book provides details on the majority of sensors for aircraft and many for spacecraft satellites and space probes It is written by an international team of twelve authors representing four countries from Eastern and Western Europe and North America all with considerable experience in aerospace sensor and systems design Highlights include coverage of aerospace vehicle classification specific design criteria and the requirements of onboard systems and sensors reviews of airborne flight parameter sensors weather sensors and collision avoidance devices discussions on the important role of inertial navigation systems INS and separate gyroscopic sensors for aerospace vehicle navigation and motion control descriptions of engine parameter information collection systems including fuel quantity and consumption sensors pressure pick ups tachometers vibration control and temperature sensors and descriptions and examples of sensor integration

Satellite Navigation Advances Aiden Feynman,AI,2025-03-12 Satellite Navigation Advances explores how global positioning systems GPS and satellite technology are transforming transportation It highlights how precise location data is now essential for everything from personal navigation to complex logistics The book traces the evolution of navigation from celestial observations to advanced satellite networks like GPS GLONASS BeiDou and Galileo underlining the technological and geopolitical influences driving the field The book argues that innovations in signal processing and data analytics are fundamentally improving positioning navigation and timing PNT

services For example the book will examine how satellite navigation enhances route optimization for trucks accuracy in shipping lanes and precision approaches for aviation It examines specific applications within land maritime and air transportation It also analyzes data from government agencies and research papers to assess GNSS performance and the impact of atmospheric conditions on signal accuracy The book uniquely bridges the gap between technical details and practical transportation applications making it valuable for engineers scientists transportation professionals and policymakers Chapters progress from fundamental principles to specific applications concluding with perspectives on emerging technologies such as low Earth orbit LEO satellites It provides a comprehensive overview of satellite navigation while remaining accessible to those seeking to understand the technology underpinning modern navigation systems

CONAT 2024 International Congress of Automotive and Transport Engineering Anghel Chiru,Dinu Covaciu,2024-11-19 These 3 volume proceedings includes selected and reviewed papers from CONAT 2024 the 13th edition of the International Congress of Automotive and Transport Engineering held in Brasov Romania in November 2024 Authors are experts from research industry and universities coming from around the world The papers are covering the latest developments in automotive vehicles and environment advanced transport systems and road traffic advanced powertrain systems new materials manufacturing technologies and logistics accident research and analysis and innovative solutions for automotive vehicles The congress is organized by SIAR Society of Automotive Engineers from Romania in cooperation with SAE International and Transilvania University of Brasov This third volume presents the papers on Advanced Transport Systems Accident Research and Analysis and some related to History of Automotive Technics and Technology **Radar Processing, Technology, and Applications** ,1998 **Applications in Electronics and Computing Systems** Igor Dantsevich,Irina Samoylenko,2022-11-05 This book presents the materials of the IV International Conference on Applications in Electronics and Computing Systems Combining empirical and theoretical information this book demonstrates advanced cross cutting issues in various fields such as communication engineering electronics and microelectronics power systems electric machines unmanned systems and control systems The results of the research constitute the research basis in applied science of transport infrastructure and electric power systems including renewable and promising energy resources

Scientific and Technical Aerospace Reports ,1995 Lists citations with abstracts for aerospace related reports obtained from world wide sources and announces documents that have recently been entered into the NASA Scientific and Technical Information Database **Smart Ships** Kai Turing,AI,2025-03-12 Smart Ships explores the transformative impact of AI and automation on maritime navigation focusing on cargo ship efficiency and safety The book reveals how AI driven systems optimize shipping routes potentially leading to significant reductions in fuel consumption and enhanced maritime safety It also highlights the critical need for careful integration of these technologies into existing maritime infrastructure considering ethical implications and cybersecurity risks The book examines AI enhanced route optimization using predictive

weather modeling and real time traffic analysis alongside automation in shipboard operations like engine monitoring and cargo management AI driven collision avoidance systems with their potential to reduce human error are also explored It progresses by first introducing core concepts and builds to the practical applications regulatory frameworks and economic benefits of AI in shipping This book provides a balanced perspective on the benefits and challenges of maritime AI using case studies simulations and industry data to support its arguments It s designed for maritime professionals policymakers and researchers seeking a comprehensive understanding of maritime technology and the future of shipping

Advances in Maritime Technology and Engineering Carlos Guedes Soares,Tiago A. Santos,2024-05-08 Advances in Maritime Technology and Engineering comprises a collection of the papers presented at the 7th International Conference on Maritime Technology and Engineering MARTECH 2024 held in Lisbon Portugal on 14 16 May 2024 This Conference has evolved from the series of biannual national conferences in Portugal which have become an international event reflecting the internationalization of the maritime sector and its activities MARTECH 2024 is the seventh of this new series of biannual conferences This book comprises 142 contributions that were reviewed by an International Scientific Committee Advances in Maritime Technology and Engineering is dedicated to maritime transportation ports as well as maritime safety and reliability It further comprises sections dedicated to ship design cruise ship design and to the structural aspects of ship design such as ultimate strength and composites subsea structures as pipelines and to ship building and ship repair The Proceedings in Marine Technology and Ocean Engineering series is dedicated to the publication of proceedings of peer reviewed international conferences dealing with various aspects of Marine Technology and Ocean Engineering The series includes the proceedings of the following conferences the International Maritime Association of the Mediterranean IMAM conferences the Marine Structures MARSTRUCT conferences the Renewable Energies Offshore RENEW conferences and the Maritime Technology MARTECH conferences The Marine Technology and Ocean Engineering series is also open to new conferences that cover topics on the sustainable exploration of marine resources in various fields such as maritime transport and ports usage of the ocean including coastal areas nautical activities the exploration and exploitation of mineral resources the protection of the marine environment and its resources and risk analysis safety and reliability The aim of the series is to stimulate advanced education and training through the wide dissemination of the results of scientific research

Artificial Neural Networks and Machine Learning - ICANN 2022 Elias Pimenidis,Plamen Angelov,Chrisina Jayne,Antonios Papaleonidas,Mehmet Aydin,2022-09-06 The 4 volumes set of LNCS 13529 13530 13531 and 13532 constitutes the proceedings of the 31st International Conference on Artificial Neural Networks ICANN 2022 held in Bristol UK in September 2022 The total of 255 full papers presented in these proceedings was carefully reviewed and selected from 561 submissions ICANN 2022 is a dual track conference featuring tracks in brain inspired computing and machine learning and artificial neural networks with strong cross disciplinary interactions and applications Chapter Sim to Real Neural Learning with

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