Konstantinos G. Papadopoulos

PID Controller Tuning Using the Magnitude Optimum Criterion



<u>Pid Controller Tuning Using The Magnitude Optimum</u> Criterion Advances In Industrial Control

Aniruddha Datta, Ming-Tzu Ho, Shankar P. Bhattacharyya

Pid Controller Tuning Using The Magnitude Optimum Criterion Advances In Industrial Control:

Pid Controller Tuning Using the Magnitude Optimum Criterion Konstantinos Papadopoulos, 2014-11-30 PID Controller Tuning Using the Magnitude Optimum Criterion Konstantinos G. Papadopoulos, 2016-08-23 An instructive reference that will help control researchers and engineers interested in a variety of industrial processes to take advantage of a powerful tuning method for the ever popular PID control paradigm This monograph presents explicit PID tuning rules for linear control loops regardless of process complexity It shows the reader how such loops achieve zero steady position velocity and acceleration errors and are thus able to track fast reference signals. The theoretical development takes place in the frequency domain by introducing a general transfer function known process model and by exploiting the principle of the magnitude optimum criterion It is paralleled by the presentation of real industrial control loops used in electric motor drives The application of the proposed tuning rules to a large class of processes shows that irrespective of the complexity of the controlled process the shape of the step and frequency response of the control loop exhibits a specific performance This specific performance along with the PID explicit solution formulates the basis for developing an automatic tuning method for the PID controller parameters which is a problem often met in many industry applications temperature pH and humidity control ratio control in product blending and boiler drum level control for example The process of the model is considered unknown and controller parameters are tuned automatically such that the aforementioned performance is achieved The potential both for the explicit tuning rules and the automatic tuning method is demonstrated using several examples for Advances in Soft Computing, Intelligent benchmark process models recurring frequently in many industry applications Robotics and Control János Fodor, Robert Fullér, 2014-03-20 Soft computing intelligent robotics and control are in the core interest of contemporary engineering Essential characteristics of soft computing methods are the ability to handle vague information to apply human like reasoning their learning capability and ease of application Soft computing techniques are widely applied in the control of dynamic systems including mobile robots The present volume is a collection of 20 chapters written by respectable experts of the fields addressing various theoretical and practical aspects in soft computing intelligent robotics and control The first part of the book concerns with issues of intelligent robotics including robust xed point transformation design experimental verification of the input output feedback linearization of differentially driven mobile robot and applying kinematic synthesis to micro electro mechanical systems design The second part of the book is devoted to fundamental aspects of soft computing This includes practical aspects of fuzzy rule interpolation subjective weights based meta learning in multi criteria decision making swarm based heuristics for an area exploration and knowledge driven adaptive product representations The last part addresses different problems issues and methods of applied mathematics This includes perturbation estimates for invariant subspaces of Hessenberg matrices uncertainty and nonlinearity modelling by probabilistic metric spaces and comparison and visualization of the DNA of six primates **Proceedings, the Irish Signals**

and Systems Conference 2004 Sakir Sezer, Sean McLoone, Dr. Uwe Krüger, 2004 Over the past 12 years ISSC has been a major forum for engineers and young researchers in Ireland on communications control and DSP The conference has established itself as one of the premier conferences in Ireland addressing all aspects of signals and systems including design implementation algorithms modelling and performance This conference continued this tradition under the auspices of the IEE and for the first time the ISSC conference proceedings are published by the IEE and indexed by INSPEC PID Control Kok K. Tan, Qing-Guo Wang, Chang C. Hang, 2012-12-06 Recently a great deal of effort has been dedicated to capitalising on advances in mathematical control theory in conjunction with tried and tested classical control structures particularly with regard to the enhanced robustness and tighter control of modern PID controllers Much of the research in this field and that of the operational autonomy of PID controllers has already been translated into useful new functions for industrial controllers This book covers the important knowledge relating to the background application and design of and advances in PID controllers in a unified and comprehensive treatment including Evolution and components of PID controllers Classical and Modern PID controller design Automatic Tuning Multi loop Control Practical issues concerned with PID control The book is intended to be useful to a wide spectrum of readers interested in PID control ranging from practising technicians and engineers to graduate and undergraduate students Non-parametric Tuning of PID Controllers Igor Boiko, 2012-08-22 The relay feedback test RFT has become a popular and efficient in process identification and automatic controller tuning Non parametric Tuning of PID Controllers couples new modifications of classical RFT with application specific optimal tuning rules to form a non parametric method of test and tuning Test and tuning are coordinated through a set of common parameters so that a PID controller can obtain the desired gain or phase margins in a system exactly even with unknown process dynamics The concept of process specific optimal tuning rules in the nonparametric setup with corresponding tuning rules for flow level pressure and temperature control loops is presented in the text Common problems of tuning accuracy based on parametric and non parametric approaches are addressed In addition the text treats the parametric approach to tuning based on the modified RFT approach and the exact model of oscillations in the system under test using the locus of a perturbed relay system LPRS method Industrial loop tuning for distributed control systems using modified RFT is also described Many of the problems of tuning rules optimization and identification with modified RFT are accompanied by MATLAB code downloadable from http extras springer com 978 1 4471 4464 9 to allow the reader to duplicate the results Non parametric Tuning of PID Controllers is written for readers with previous knowledge of linear control and will be of interest to academic control researchers and graduate students and to practitioners working in a variety of chemical mechanical and process engineering related industries PID Control in the Third Millennium Ramon Vilanova, Antonio Visioli, 2012-02-05 The early 21st century has seen a renewed interest in research in the widely adopted proportional integral differential PID form of control PID Control in the Third Millennium provides an overview of

the advances made as a result Featuring new approaches for controller tuning control structures and configurations for more efficient control practical issues in PID implementation and non standard approaches to PID including fractional order event based nonlinear data driven and predictive control the nearly twenty chapters provide a state of the art resum of PID controller theory design and realization Each chapter has specialist authorship and ideas clearly characterized from both academic and industrial viewpoints PID Control in the Third Millennium is of interest to academics requiring a reference for the current state of PID related research and a stimulus for further inquiry Industrial practitioners and manufacturers of control systems with application problems relating to PID will find this to be a practical source of appropriate and advanced Handbook of PI and PID Controller Tuning Rules Aidan O'Dwyer, 2009 The vast majority of automatic controllers used to compensate industrial processes are PI or PID type This book comprehensively compiles using a unified notation tuning rules for these controllers proposed from 1935 to 2008 The tuning rules are carefully categorized and application information about each rule is given The book discusses controller architecture and process modeling issues as well as the performance and robustness of loops compensated with PI or PID controllers This unique publication brings together in an easy to use format material previously published in a large number of papers and books This wholly revised third edition extends the presentation of PI and PID controller tuning rules for single variable processes with time delays to include additional rules compiled since the second edition was published in 2006 **Model-Reference Robust Tuning of PID Controllers** Victor M. Alfaro, Ramon Vilanova, 2016-04-16 This book presents a unified methodology for the design of PID controllers that encompasses the wide range of different dynamics to be found in industrial processes. This is extended to provide a coherent way of dealing with the tuning of PID controllers The particular method at the core of the book is the so called model reference robust tuning MoReRT developed by the authors MoReRT constitutes a novel and powerful way of thinking of a robust design and taking into account the usual design trade offs encountered in any control design problem The book starts by presenting the different two degree of freedom PID control algorithm variations and their conversion relations as well as the indexes used for performance robustness and fragility evaluation the bases of the proposed model Secondly the MoReRT design methodology and normalized controlled process models and controllers used in the design are described in order to facilitate the formulation of the different design problems and subsequent derivation of tuning rules Inlater chapters the application of MoReRT to over damped inverse response integrating and unstable processes is described The book ends by presenting three possible extensions of the MoReRT methodology thereby opening the door to new research developments In this way the book serves as a reference and source book for academic researchers who may also consider it as a stimulus for new ideas as well as for industrial practitioners and manufacturers of control systems who will find appropriate advanced solutions to many application problems PID Control for Industrial Processes Mohammad Shamsuzzoha, 2018-09-12 PID Control for Industrial Processes presents a clear multidimensional representation of

proportional integral derivative PID control for both students and specialists working in the area of PID control It mainly focuses on the theory and application of PID control in industrial processes It incorporates recent developments in PID control technology in industrial practice Emphasis has been given to finding the best possible approach to develop a simple and optimal solution for industrial users This book includes several chapters that cover a broad range of topics and priority has been given to subjects that cover real world examples and case studies. The book is focused on approaches for controller tuning i e method bases on open loop plant tests and closed loop experiments Handbook Of Pi And Pid Controller Tuning Rules (2nd Edition) Aidan O'dwyer, 2006-02-15 The vast majority of automatic controllers used to compensate industrial processes are of PI or PID type This book comprehensively compiles using a unified notation tuning rules for these controllers proposed over the last seven decades 1935 2005 The tuning rules are carefully categorized and application information about each rule is given The book discusses controller architecture and process modeling issues as well as the performance and robustness of loops compensated with PI or PID controllers This unique publication brings together in an easy to use format material previously published in a large number of papers and books This wholly revised second edition extends the presentation of PI and PID controller tuning rules for single variable processes with time delays to include additional rules compiled since the first edition was published in 2003 a Industrial PID Controller Tuning José David Rojas, Orlando Arrieta, Ramon Vilanova, 2021-05-22 Industrial PID Controller Tuning presents a different view of the servo regulator compromise that has been studied for a long time in industrial control research Optimal tuning generally involves comparison of cost functions e g a quadratic function of the error or a time weighted absolute value of the error but without taking advantage of available multi objective optimization methods The book does make use of multi objective optimization to account for several sources of disturbance applying them to a more realistic problem how to select the tuning of a controller when both servo and regulator responses are important The authors review the different deterministic multi objective optimization methods In order to ameliorate the consequences of the computational expense typically involved in their use specifically the generation of multiple solutions among which the control engineer still has to choose algorithms for two degree of freedom PID control are implemented in MATLAB MATLAB code and a MATLAB compatible program are provided for download and will help readers to adapt the ideas presented in the text for use in their own systems Further practical guidance is offered by the inclusion of several examples of common industrial processes amenable to the use of the authors methods Researchers interested in non heuristic approaches to controller tuning or in decision making after a Pareto set has been established and graduate students interested in beginning a career working with PID control and or industrial controller tuning will find this book a valuable reference and source of ideas Advances in Industrial Control reports and encourages the transfer of technology in control engineering. The rapid development of control technology has an impact on all areas of the control discipline The series offers an opportunity for researchers to present an extended exposition of new

work in all aspects of industrial control Magnitude Optimum Techniques for PID Controllers Damir Vrančić, 2012 Magnitude Optimum Techniques for PID Controllers Structure and Synthesis of PID Controllers Aniruddha Datta, Ming-Tzu Ho, Shankar P. Bhattacharvya, 2013-03-14 In many industrial applications the existing constraints mandate the use of controllers of low and fixed order while typically modern methods of optimal control produce high order controllers The authors seek to start to bridge the resultant gap and present a novel methodology for the design of low order controllers such as those of the P PI and PID types Written in a self contained and tutorial fashion this book first develops a fundamental result generalizing a classical stability theorem the Hermite Biehler Theorem and then applies it to designing controllers that are widely used in industry It contains material on current techniques for PID controller design stabilization of linear time invariant plants using PID controllers optimal design with PID controllers robust and non fragile PID controller design stabilization of first order systems with time delay constant gain stabilization with desired damping constant gain stabilization of discrete time plants PID Controller Design Approaches Marialena Vagia, 2012-03-28 First placed on the market in 1939 the design of PID controllers remains a challenging area that requires new approaches to solving PID tuning problems while capturing the effects of noise and process variations. The augmented complexity of modern applications concerning areas like automotive applications microsystems technology pneumatic mechanisms dc motors industry processes require controllers that incorporate into their design important characteristics of the systems These characteristics include but are not limited to model uncertainties system s nonlinearities time delays disturbance rejection requirements and performance criteria The scope of this book is to propose different PID controllers designs for numerous modern technology applications in order to cover the needs of an audience including researchers scholars and professionals who are interested in advances in PID controllers and related topics Advances in PID Control Valery D. Yurkevich, 2011-09-06 Since the foundation and up to the current state of the art in control engineering the problems of PID control steadily attract great attention of numerous researchers and remain inexhaustible source of new ideas for process of control system design and industrial applications PID control effectiveness is usually caused by the nature of dynamical processes conditioned that the majority of the industrial dynamical processes are well described by simple dynamic model of the first or second order The efficacy of PID controllers vastly falls in case of complicated dynamics nonlinearities and varying parameters of the plant This gives a pulse to further researches in the field of PID control Consequently the problems of advanced PID control system design methodologies rules of adaptive PID control self tuning procedures and particularly robustness and transient performance for nonlinear systems still remain as the areas of the lively interests for many scientists and researchers at the present time The recent research results presented in this book provide new ideas for improved performance of PID control applications PID Control - New Design Methods and Applications Constantin Volosencu, 2025-01-22 The subjects in the book PID Control New Design Methods and Applications chapters range from fundamental aspects of PID Proportional

Integral Derivative controller design theory to industrial applications and complex process control systems. The book covers topics such as basic considerations for the digital implementation of PID Controllers tuning methods of fuzzy PI controllers analytical design of a closed control loop controller identification and control of unstable systems using PITOPS Process. Identification and Controller Tuning Optimizer Simulator and the design and development of servo drive control system based on DSP Digital Signal Processor The book highlights several advantages including the efficiency of PID Proportional Integral Derivative controllers which is demonstrated both theoretically and practically showcasing their fast and stable response It also emphasizes their ability to reduce errors and improve the performance of control systems as well as their simplicity ease of tuning and the practical methods presented to enhance PID controllers. The book is intended for a broad audience including academics and industrial specialists such as professors researchers designers and students. *Practical PID Control* Antonio Visioli,2006-11-03 This book focuses on those functionalities that can provide significant improvements in Proportional integral derivative PID performance in combination with parameter tuning In particular the choice of filter to make the controller proper the use of a feedforward action and the selection of an anti windup strategy are addressed The book gives the reader new methods for improving the performance of the most widely applied form of control in industry

Handbook Of Pi And Pid Controller Tuning Rules (3rd Edition) Aidan O'dwyer, 2009-06-15 The vast majority of automatic controllers used to compensate industrial processes are PI or PID type This book comprehensively compiles using a unified notation tuning rules for these controllers proposed from 1935 to 2008 The tuning rules are carefully categorized and application information about each rule is given The book discusses controller architecture and process modeling issues as well as the performance and robustness of loops compensated with PI or PID controllers This unique publication brings together in an easy to use format material previously published in a large number of papers and books This wholly revised third edition extends the presentation of PI and PID controller tuning rules for single variable processes with time delays to include additional rules compiled since the second edition was published in 2006 a Introduction to PID Controllers Rames C. Panda, 2012-02-29 This book discusses the theory application and practice of PID control technology It is designed for engineers researchers students of process control and industry professionals It will also be of interest for those seeking an overview of the subject of green automation who need to procure single loop and multi loop PID controllers and who aim for an exceptional stable and robust closed loop performance through process automation Process modeling controller design and analyses using conventional and heuristic schemes are explained through different applications here The readers should have primary knowledge of transfer functions poles zeros regulation concepts and background The following sections are covered The Theory of PID Controllers and their Design Methods Tuning Criteria Multivariable Systems Automatic Tuning and Adaptation Intelligent PID Control Discrete Intelligent PID Controller Fractional Order PID Controllers Extended Applications of PID and Practical Applications A wide variety of researchers and engineers seeking methods of designing and

analyzing controllers will create a heavy demand for this book interdisciplinary researchers real time process developers control engineers instrument technicians and many more entities that are recognizing the value of shifting to PID controller procurement

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