



Vanderlei Bonato
Eduardo Marques

Embedded Robotics

A Hardware Architecture for Simultaneous
Localization and Mapping of Mobile Robots



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Embedded Robotics A Hardware Architecture For Simultaneous Localization And Mapping Of Mobile Robots

Thomas Bräunl



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Digital Technologies and Applications Saad Motahhir,Badre Bossofi,2022-05-07 This book presents Volume 1 of selected research papers presented at the Second International Conference on Digital Technologies and Applications ICDTA 22 held at Sidi Mohamed Ben Abdellah University Fez Morocco on January 28 29 2022 This book highlights the latest innovations in digital technologies as artificial intelligence Internet of Things embedded systems network technology information processing and their applications in several areas as hybrid vehicles renewable energy mechatronics medicine This book will encourage and inspire researchers industry professionals and policymakers to put these methods into practice

Reconfigurable Computing: Architectures, Tools, and Applications Roger Woods,Katherine Compton,Christos Bourganis,Pedro C. Diniz,2008-08-29 Coverage in this proceedings volume includes DNA and string processing applications reconfigurable computing hardware and systems image processing run time behavior instruction set extension as well as random number generation and financial computation

Enabling Machine Learning Applications in Data Science Aboul Ella Hassanien,Ashraf Darwish,Sherine M. Abd El-Kader,Dabiah Ahmed Alboaneen,2021-05-27 This book gathers selected high quality research papers presented at Arab Conference for Emerging Technologies 2020 organized virtually in Cairo during 21 23 June 2020 This book emphasizes the role and recent developments in the field of emerging technologies and artificial intelligence and related technologies with a special focus on sustainable development in the Arab world The book targets high quality scientific research papers with applications including theory practical prototypes new ideas case studies and surveys which cover machine learning applications in data science

Modern Artificial Intelligence and Data Science 2024 Abdellah Idrissi,2024-10-03 This book through its various chapters presenting recent advances in Modern Artificial Intelligence and Data Science as well as their applications aims to set up lasting and real applications necessary for both academics and professionals By its proposals of new ideas it serves as a real guide both to informed readers and to beginners in these specialized fields It also covers applications that discuss how they can support societal challenges such as education health agriculture clean energy business environment and security Readers will find here the fruit of many research ideas covering a wide range of application areas that can be explored for the advancement of their research or the development of their business These ideas present new techniques and trends projected in various areas of daily life This book is therefore intended for Designers Developers Decision Makers Consultants Engineers and of course Master s Doctorate Students Researchers and Universities

Emerging Trends in Computational Biology, Bioinformatics, and Systems Biology Hamid R Arabnia,Quoc Nam Tran,2015-08-11 Emerging Trends in Computational Biology Bioinformatics and Systems Biology discusses the latest developments in all aspects of computational biology bioinformatics and systems biology and the application of data analytics and algorithms mathematical modeling and simulation techniques Discusses the development and application of data analytical and theoretical methods mathematical modeling and computational simulation

techniques to the study of biological and behavioral systems including applications in cancer research computational intelligence and drug design high performance computing and biology as well as cloud and grid computing for the storage and access of big data sets Presents a systematic approach for storing retrieving organizing and analyzing biological data using software tools with applications to general principles of DNA RNA structure bioinformatics and applications genomes protein structure and modeling and classification as well as microarray analysis Provides a systems biology perspective including general guidelines and techniques for obtaining integrating and analyzing complex data sets from multiple experimental sources using computational tools and software Topics covered include phenomics genomics epigenomics epigenetics metabolomics cell cycle and checkpoint control and systems biology and vaccination research Explains how to effectively harness the power of Big Data tools when data sets are so large and complex that it is difficult to process them using conventional database management systems or traditional data processing applications Discusses the development and application of data analytical and theoretical methods mathematical modeling and computational simulation techniques to the study of biological and behavioral systems Presents a systematic approach for storing retrieving organizing and analyzing biological data using software tools with applications Provides a systems biology perspective including general guidelines and techniques for obtaining integrating and analyzing complex data sets from multiple experimental sources using computational tools and software

Cooperative Robots and Sensor Networks 2015 Anis Koubâa,J.Ramiro Martínez-de Dios,2015-05-18 This book compiles some of the latest research in cooperation between robots and sensor networks Structured in twelve chapters this book addresses fundamental theoretical implementation and experimentation issues The chapters are organized into four parts namely multi robots systems data fusion and localization security and dependability and mobility

Intelligent Systems and Networks Duc-Tan Tran,Gwanggil Jeon,Thi Dieu Linh Nguyen,Joan Lu,Thu-Do Xuan,2021-05-12 This book presents Proceedings of the International Conference on Intelligent Systems and Networks ICISN 2021 held at Hanoi in Vietnam It includes peer reviewed high quality articles on intelligent system and networks It brings together professionals and researchers in the area and presents a platform for exchange of ideas and to foster future collaboration The topics covered in this book include foundations of computer science computational intelligence language and speech processing software engineering software development methods wireless communications signal processing for communications electronics track IoT and sensor systems embedded systems etc

Embedded Robotics Vanderlei Bonato,Eduardo Marques,2011-09 This book presents a hardware architecture for the Simultaneous Localization And Mapping SLAM problem applied to embedded robots The architecture is composed by highly specialized modules for robot localization and feature based map building from images obtained directly from CMOS cameras in real time The system is completely embedded on a Field Programmable Gate Array FPGA device where several hardware orientated optimizations are exploited The main modules of the architecture are the Extended Kalman Filter EKF and the feature detection system

based on the SIFT Scale Invariant Feature Transform algorithm. Additionally, this book also presents basic concepts about mapping and state of the art algorithms for SLAM with monocular and stereo vision. **Chinese Journal of Electronics**, 2007

Simultaneous Localization and Mapping for Mobile Robots: Introduction and Methods Fernández-Madrigal, Juan-Antonio, 2012-09-30 As mobile robots become more common in general knowledge and practices as opposed to simply in research labs, there is an increased need for the introduction and methods to Simultaneous Localization and Mapping. SLAM and its techniques and concepts related to robotics. *Simultaneous Localization and Mapping for Mobile Robots: Introduction and Methods* investigates the complexities of the theory of probabilistic localization and mapping of mobile robots as well as providing the most current and concrete developments. This reference source aims to be useful for practitioners, graduate and postgraduate students, and active researchers alike. **Embedded Robotics** Thomas Bräunl, 2008-09-10 This book presents a unique examination of mobile robots and embedded systems from introductory to intermediate level. It is structured in three parts dealing with Embedded Systems, hardware and software design, actuators, sensors, PID control, multitasking, Mobile Robot Design, driving, balancing, walking, and flying robots, and Mobile Robot Applications, mapping, robot soccer, genetic algorithms, neural networks, behavior based systems, and simulation. The book is organized for ease of use with side texts and lots of figures, photographs, and worked example programs. A complementary web site offers free download of the RoBIOS operating system, example programs, online documentation, and a simulator. The book is written as a text for courses in computer science, computer engineering, IT, electronic engineering, and mechatronics, as well as a guide for robot hobbyists and researchers. **BOOK JACKET**

Localization and Mapping of Autonomous Mobile Robots Junzhi Yu, Zhiqiang Cao, Peiyu Guan, Chengpeng Wang, 2025-10-31 Localization and mapping play a critical role in the autonomous task execution of mobile robots. This book covers the theoretical and technological aspects of robot localization and mapping, including visual localization and mapping, visual relocalization, LiDAR localization and mapping, and place recognition. It provides the theoretical foundations of robot localization and mapping. It employs both traditional methods such as geometry-based visual localization and state of the art deep learning techniques that improve robot perception. The authors also address LiDAR-based localization, exploring techniques to improve both efficiency and accuracy when processing dense point clouds. Key topics include visual localization using deep features, integration of visual solutions under ROS-based software architecture, and distribution-based LiDAR localization. This book will be of great interest to students and professionals in the fields of robotics and artificial intelligence. It will also be an excellent reference for engineers and technicians involved in the development of robot localization.

A Simultaneous Localization and Mapping Implementation Using Inexpensive Hardware Todd Michael Ayccock, 2010 Autonomous mobile robots have become more popular over the past few decades, influencing both industry and academia. The strategy of making robots navigate autonomously adds many problems, however. Many of these problems are directly related to the robot's ability to localize and

autonomously map its environment A solution to this problem is called simultaneous localization and mapping SLAM SLAM is the concept of localizing the robot while simultaneously generating a map of the environment and then using the map in subsequent localization steps The success of SLAM lies in a filter algorithm One of the more common and successful filters is the extended Kalman filter EKF and there are many different algorithms that could be used to implement this filter However the computational complexity and physical cost of implementing the algorithm place the SLAM solution beyond the scope of many low cost robotics projects This thesis analyzes many of these cost issues related to the implementation of SLAM on autonomous robots First the types of sensing hardware are discussed and potential low cost solutions are suggested Next timing aspects of two different methods for data association are examined in order to evaluate tradeoffs between speed and accuracy Finally optimizations to the filter's update step involving matrix multiplication are presented These three changes are presented as a customized EKF SLAM algorithm called inexpensive hardware SLAM IH SLAM which is applicable to small scale robotics applications

Mobile Robot Localization and Map Building Jose A. Castellanos, Juan D.

Tardós, 2012-12-06 During the last decade many researchers have dedicated their efforts to constructing revolutionary machines and to providing them with forms of artificial intelligence to perform some of the most hazardous risky or monotonous tasks historically assigned to human beings Among those machines mobile robots are undoubtedly at the cutting edge of current research directions A rough classification of mobile robots can be considered on the one hand mobile robots oriented to human made indoor environments on the other hand mobile robots oriented to unstructured outdoor environments which could include flying oriented robots space oriented robots and underwater robots The most common motion mechanism for surface mobile robots is the wheel based mechanism adapted both to flat surfaces found in human made environments and to rough terrain found in outdoor environments However some researchers have reported successful developments with leg based mobile robots capable of climbing up stairs although they require further investigation The research work presented here focuses on wheel based mobile robots that navigate in human made indoor environments The main problems described throughout this book are Representation and integration of uncertain geometric information by means of the Symmetries and Perturbations Model SPmodel This model combines the use of probability theory to represent the imprecision in the location of a geometric element and the theory of symmetries to represent the partiality due to characteristics of each type of geometric element A solution to the first location problem that is the computation of an estimation for the mobile robot location when the vehicle is completely lost in the environment The problem is formulated as a search in an interpretation tree using efficient matching algorithms and geometric constraints to reduce the size of the solution space The book proposes a new probabilistic framework adapted to the problem of simultaneous localization and map building for mobile robots the Symmetries and Perturbations Map SPmap This framework has been experimentally validated by a complete experiment which profited from ground truth to accurately validate the precision and the

appropriateness of the approach The book emphasizes the generality of the solutions proposed to the different problems and their independence with respect to the exteroceptive sensors mounted on the mobile robot Theoretical results are complemented by real experiments where the use of multisensor based approaches is highlighted Mobile Robot Programming Toolkit Fouad Sabry, 2025-01-21 Mobile Robot Programming Toolkit is an essential resource for anyone looking to delve into the dynamic world of robotics programming Written for professionals undergraduate and graduate students enthusiasts and hobbyists this book offers a practical guide to building understanding and programming mobile robots By blending theory with hands-on approaches the book empowers readers to apply cutting-edge techniques in robot navigation mapping and artificial intelligence Chapters Brief Overview Mobile Robot Programming Toolkit Introduction to mobile robot programming fundamentals software setup and essential tools for developing robotic systems Boids Explore the Boids algorithm for simulating flocking behavior and its application in swarm robotics Neuroevolution Learn about neuroevolution techniques to optimize robotic control systems and enhance performance over time Robotic mapping Understand the core concepts of robotic mapping including techniques for creating accurate environment representations Simultaneous localization and mapping Discover methods for enabling robots to map their surroundings while simultaneously determining their position Iterative closest point An introduction to the ICP algorithm key for refining 3D object models and improving robot localization accuracy Software visualization Learn how to visualize robotic software to enhance debugging testing and optimization processes Hilbert curve Gain insight into the Hilbert curve's role in improving spatial data processing and navigation in mobile robots Nearest neighbor search Delve into algorithms for efficiently finding the nearest neighbors in datasets a crucial aspect of robot decision-making Collaborative mapping Discover collaborative mapping techniques that allow multiple robots to work together to create detailed maps of unknown environments Indoor positioning system Explore the concepts behind indoor positioning systems which are essential for robots operating in GPS-denied environments Robot navigation Understand the principles of autonomous robot navigation including path planning obstacle avoidance and decision-making Visual odometry Learn about visual odometry methods used for estimating a robot's position and movement using camera inputs Omnidirectional 360-degree camera Understand the significance of 360-degree cameras for enhanced robot perception and navigation Opensource robotics Explore the world of opensource robotics software tools and platforms for creating customizable robotic systems Software map Learn how to create and manage software maps for robotic systems enhancing their efficiency and adaptability Robotics Toolbox for MATLAB Get hands-on experience with the Robotics Toolbox for MATLAB a powerful tool for modeling and simulating robots Cloud robotics Understand the emerging field of cloud robotics and its potential to revolutionize robot collaboration computation and data sharing Margarita Chli Gain insight into Margarita Chli's contributions to robotics particularly in robot vision and artificial intelligence Jürgen Sturm Explore Jürgen Sturm's work in the fields of visual perception simultaneous localization and mapping for mobile robots Flocking Study the

principles of flocking behavior in robotics where robots mimic the coordinated movement patterns of animals This book is an invaluable tool that blends practical techniques with theoretical principles making it an indispensable guide for those working in or studying the field of robotics Whether you re programming your first robot or exploring advanced techniques in artificial intelligence *Mobile Robot Programming Toolkit* provides the knowledge to take your work to the next level

Mobile Robots Navigation Alejandra Barrera,2010-03-01 Mobile robots navigation includes different interrelated activities i perception as obtaining and interpreting sensory information ii exploration as the strategy that guides the robot to select the next direction to go iii mapping involving the construction of a spatial representation by using the sensory information perceived iv localization as the strategy to estimate the robot position within the spatial map v path planning as the strategy to find a path towards a goal location being optimal or not and vi path execution where motor actions are determined and adapted to environmental changes The book addresses those activities by integrating results from the research work of several authors all over the world Research cases are documented in 32 chapters organized within 7 categories next described *Service Robotics* ,2020-11-26 We feel the impact of robots on our lives more and more every day Service robots constitute the broadest and the most exciting applications in this field such as personal care and assistance agriculture logistics mobility medical and defense oriented robots Since service robotics contains many different types of robots the variety of problems to be solved is also large Many popular robotic problems ranging from mechanism design to simultaneous localization and mapping SLAM from motion planning to system security can be examined in this context You will find various examples and solutions for this critical area of robotics in this book We hope that researchers interested in the subject will benefit from this book *3D Robotic Mapping* Andreas Nüchter,2008-12-18 Focuses on acquiring spatial models of physical environments through mobile robots The robotic mapping problem is commonly referred to as SLAM simultaneous localization and mapping 3D maps are necessary to avoid collisions with complex obstacles and to self localize in six degrees of freedom x y z position roll yaw and pitch angle New solutions to the 6D SLAM problem for 3D laser scans are proposed and a wide variety of applications are presented **Embedded Robotics: Mobile robot applications** Thomas Bräunl,2008 This book presents a unique combination of mobile robots and embedded systems from introductory to intermediate level It is structured in three parts dealing with embedded systems hardware and software design actuators sensors PID control multitasking wireless communication mobile robot design driving balancing walking and flying robots and mobile robot applications mapping robot soccer genetic algorithms neural networks behavior based systems and simulation Its third edition has been significantly extended with new chapters on CPUs robot manipulators and automotive systems as well as additional material in the chapters on navigation localization neural networks and genetic algorithms This results in a much more complete treatment of the subject area and an even more well rounded publication that contains up to date research results The book is written as a text for courses in computer science computer engineering

IT electronic engineering and mechatronics as well as a guide for robot hobbyists and researchers *Robotic Exploration and Landmark Determination* K. Sridharan, Panakala Rajesh Kumar, 2007-12-22 Much of the research effort in mobile robots in the recent past has been on sensing and design of time efficient algorithms for tasks such as localization mapping and navigation Mobile robots typically employ an embedded computer for high level computations As applications of robots expand there is a need to investigate architecturally efficient choices for this embedded computing platform In particular it is valuable to process data to obtain time space and energy efficient solutions for various robotic tasks This book presents hardware efficient algorithms and FPGA implementations for two robotic tasks namely exploration and landmark determination The work identifies scenarios for mobile robotics where parallel processing and selective shutdown offered by FPGAs are invaluable The book proceeds to systematically develop memory driven VLSI architectures for both the tasks The architectures are ported to a low cost FPGA with a fairly small number of system gates A robot fabricated with this FPGA on board serves to validate the efficacy of the approach Numerous experiments with the robot are reported

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